

# New Soliton Solutions Arising in Some NLEEs 

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#### Abstract

We have worked on (2+1)-dimensional dissipative long wave system (DLWS) and ( $2+1$ )-dimensional Date-Jimbo-Kashiwara-Miwa (DJKM) equation. We have applied GKM, which has been obtained by generalizing the Kudryashov method, to the ( $2+1$ )- dimensional DLWS and ( $2+1$ )-dimensional DJKM equation. Thus, we have got some new soliton solutions of handled system and equation. We have plotted 2D and 3D surfaces of these acquired results by using Wolfram Mathematica 12. Then, we have shown the validity of the acquired solutions.


## 1. Introduction

Nonlinear evolution equations (NLEEs) have very significant applications in areas such as mathematical physics, biology, economy, mathematical chemistry, hydrodynamics, fluid dynamics, geochemistry, control theory, meteorology, optics, mechanics, chemical kinematics, biophysics, biogenetics, and so on. Particularly nonlinear partial differential equations, researching chemical reactions occurring in various scientific environments, changes in living populations, heat dissipation on metals, determination of charge and current in electrical circuits, plate and wire vibrations; It is widely used in the study and interpretation of important physical phenomena such as sea, lake, stream and tidal waves, decay of a radioactive object. Various studies are carried out by many scientists to find the solutions of equations, which have such extremely important and widespread areas of use (Ali et al., 2021; Yokus et al., 2020;

Gao et al., 2020; Cinar et al., 2021; Rani et al., 2021; Manafian et al., 2020; Yaslan and Girgin, 2019; Ghanbari and Inc, 2018; Dusunceli et al., 2021; Kumar and Kaplan, 2018; Mirzazadeh et al., 2021). (2+1)-dimensional DLWS is a famous system of equations used in physical applications, nonlinear science and nonlinear wave theory (Chang et al., 2020). (2+1)-dimensional DLWS is given as (Yang and Feng, 2021):
$u_{t}-u_{x x}-2 u_{x} v-2 u v_{x}=0$,
$v_{t y}+v_{x x y}-2 u_{x x}-2 v_{x} v_{y}-2 \nu v_{x y}=0$.
Chang et al. used Lie symmetry analysis and dynamical system method for system (Chang et al., 2020). Yang and Feng obtained the solutions of this system by applying the variable separation method and $\exp (-\Phi(\xi))$-expansion method (Yang and Feng, 2021).
$(2+1)$-dimensional DJKM equation is given as (Yuan et al.,

[^0]2017; Pu and Hu , 2019; Ismael et al., 2020):
$u_{x x x x y}+4 u_{x x y} u_{x}+2 u_{x x x} u_{y}+6 u_{x y} u_{x x}+u_{y y y}-2 u_{x x t}=0$,
Pu and Hu examined solitary wave solutions of the equation with the sine-Gordon expansion method ( Pu and $\mathrm{Hu}, 2019$ ). Ismael et al. applied Hirota bilinear method to the equation (Ismael et al., 2020). Yuan et al. obtained solutions of the equation with Hirota method and auxiliary variable (Yuan et al., 2017). Adem et al. performed extended transformed rational function algorithm to the equation (Adem et al., 2019). Singh and Gupta applied the Pickering's algorithm to the equation (Singh and Gupta, 2018). Guo and Lin used the direct ansatz method for the equation (Guo and Lin, 2019).
In this study, GKM, which is one of the solution methods of NLEEs, is discussed (Tuluce Demiray, 2020; Tuluce Demiray and Bayrakci, 2021; Pandır and Eren, 2021; Kaplan and Akbulut, 2021; Gurefe, 2020; Islam et al. 2019). Firstly, the structure of the method is introduced. Afterwards, some soliton solutions of $(2+1)$-dimensional DJKM and $(2+1)$ dimensional DLWS were obtained by applying GKM.

## 2. Structure of GKM

We take into account a general nonlinear partial differential equation (NLPDE) for a function $v$ of three different variables in the following form:

$$
\begin{equation*}
R\left(v, v_{t}, v_{y}, v_{x}, v_{x x}, \ldots\right)=0 \tag{3}
\end{equation*}
$$

Step1: Firstly, we regard the travelling wave transform as following form;

$$
\begin{equation*}
v(x, y, t)=v(\eta), \quad \eta=x+y-m t \tag{4}
\end{equation*}
$$

Eq. (3) is turned into ordinary differential equation by Eq. (4):

$$
\begin{equation*}
L\left(t, y, x, v, v^{\prime}, v^{\prime \prime}, \ldots\right)=0 \tag{5}
\end{equation*}
$$

where superscripts demonstrate ordinary derivatives according $\eta$.

Step2: Suppose that we consider the solutions of Eq. (5) as:
$v(\eta)=\frac{\sum_{i=0}^{k} a_{i} Q^{i}(\eta)}{\sum_{j=0}^{l} b_{j} Q^{j}(\eta)}=\frac{P[Q(\eta)]}{S[Q(\eta)]}$,
where $Q$ is $\frac{1}{1 \pm e^{\eta}}$. We should point out that $Q$ is the solution to the following equation.
$Q_{\eta}=Q^{2}-Q$.

Step3: The solution of the nonlinear ordinary differential equation given by Eq. (5) is sought according to the GKM as follows:
$v(\eta)=\frac{a_{0}+a_{1} Q+a_{2} Q^{2}+\cdots+a_{k} Q^{k}}{b_{0}+b_{1} Q+b_{2} Q^{2}+\cdots+b_{l} Q^{l}}$.
If we can ascertain values of $k$ and $l$ in Eq. (6) through the homogeneous balance principle. Therefore we balance between the highest order derivative and highest order nonlinear term in Eq. (5).
Step4: We embed Eq. (6) into Eq. (5). Thus we get a polynomial $R(Q)$ of $Q$. Thereafter equalizing all coefficients of $R(Q)$ to zero, we find an algebraic equation system. By solving obtained system, we determine $c$ and coefficients of $a_{0}, a_{1}, a_{2}, \cdots, a_{k}, b_{0}, b_{1}, b_{2}, \cdots, b_{l}$. Finally, we can obtain the soliton solutions of Eq. (5).

## 3. Application of GKM to the equations

## Example 1:

For the find the soliton solutions of system (1) we consider the following transformation:

$$
\begin{equation*}
u(x, y, t)=u(\eta), v(x, y, t)=v(\eta), \eta=x+y-m t \tag{9}
\end{equation*}
$$

Putting the Eq. (9) into the system (1), we get the equation $u(x, y, t)=\frac{v^{\prime}}{2}-\frac{m v}{2}-\frac{v^{2}}{2}$. By performing the necessary mathematical operations, system (1) is converted to the following ordinary differential equation. Replace Eq. (9) into system (1) and we get the following equation,
$-m^{2} v-v^{\prime \prime}+3 m v^{2}+2 v^{3}=0$.
By using balance principle in Eq. (9), we obtain,
$k=l+1$,
If we give $l=1$ then $k=2$ we find,
$u(\eta)=\frac{a_{0}+a_{1} Q+a_{2} Q^{2}}{b_{0}+b_{1} Q}$,
$u^{\prime}(\eta)=\left(Q^{2}-Q\right) \times$
$\left[\frac{\left(a_{1}+2 a_{2} Q\right)\left(b_{0}+b_{1} Q\right)-b_{1}\left(a_{0}+a_{1} Q+a_{2} Q^{2}\right)}{\left(b_{0}+b_{1} Q\right)^{2}}\right]$,
$u^{\prime \prime}(\eta)=\frac{Q^{2}-Q}{\left(b_{0}+b_{1} Q\right)^{2}}(2 Q-1) \times$
$\left[\left(a_{1}+2 a_{2} Q\right)\left(b_{0}+b_{1} Q\right)-b_{1}\left(a_{0}+a_{1} Q+a_{2} Q^{2}\right)\right]$
$+\frac{\left(Q^{2}-Q\right)^{2}}{\left(b_{0}+b_{1} Q\right)^{3}} \times$
$\left[\begin{array}{l}2 a_{2}\left(b_{0}+b_{1} Q\right)^{2}-2 b_{1}\left(a_{1}+2 a_{2} Q\right)\left(b_{0}+b_{1} Q\right) \\ +2 b_{1}^{2}\left(a_{0}+a_{1} Q+a_{2} Q^{2}\right)\end{array}\right]$.
We obtain the soliton solutions of system (1) in the following different cases;
Case1:
$a_{0}=0, a_{1}=-b_{0}, a_{2}=-b_{1}, m=1$.
Substituting the above values in Eq. (12), we acquire the dark soliton solutions of system (1).
$u_{1}(x, y, t)=-\frac{1}{4}\left(-1+\tanh \left[\frac{x+y-t}{2}\right]\right)$
$\times\left(m+\tanh \left[\frac{x+y-t}{2}\right]\right)$,
$v_{1}(x, y, t)=-\frac{1}{2}\left(1-\tanh \left[\frac{x+y-t}{2}\right]\right)$.


Figure 1. 3D of solution (16) for $y=2,-25 \leq x \leq 25$ values with $-2 \leq t \leq 2$ range and 2D plot of solution for $t=1$ with these values.


Figure 2. 3D of solution (17) for $y=2,-20 \leq x \leq 20$ values with $-2 \leq t \leq 2$ range and 2D plot of solution for $t=1$ with these values.

Case2:
$a_{0}=b_{1}, a_{1}=-2 b_{1}, a_{2}=b_{1}, b_{0}=-\frac{b_{1}}{2}, m=2$.
Substituting the above values in Eq. (12), we acquire the darkbright and dark soliton solutions of system (1).
$u_{2}(x, y, t)=\frac{1}{4}(1+\operatorname{coth}[x+y-2 t]) \times$
$(4+4 \operatorname{coth}[x+y-2 t]+\operatorname{csch}[x+y-2 t])$,
$v_{2}(x, y, t)=-\frac{1}{2}\left(1+\operatorname{coth}\left[\frac{x+y-2 t}{2}\right]\right)^{2} \times$
$\tanh \left[\frac{x+y-2 t}{2}\right]$.


Figure 3. 3D of solution (19) for $y=2,-30 \leq x \leq 30$ values with $-5 \leq t \leq 5$ range and 2D plot of solution for $t=4$ with these values.


Figure 4. 3D of solution (20) for $y=0.5,-35 \leq x \leq 35$ values with $-3 \leq t \leq 3$ range and 2D plot of solution for $t=2$ with these values.

Case3:
$a_{0}=\frac{i b_{1}}{2 \sqrt{2}}, a_{1}=\left(1-\frac{i}{\sqrt{2}}\right) b_{1}$,
$a_{2}=-b_{1}, b_{0}=-\frac{b_{1}}{2}, m=i \sqrt{2}$.
Substituting the above values in Eq. (12), we acquire the bright soliton solutions of system (1).
$u_{3}(x, y, t)=\frac{-1}{4}+\frac{i}{2} \csc [i x+i y+\sqrt{2} t] \times$
$\tanh \left[\frac{x+y-i \sqrt{2} t}{2}\right]$,
$v_{3}(x, y, t)=-\frac{i}{\sqrt{2}}-i \csc [i x+i y+\sqrt{2} t]$.


Figure 5. 3D of solution (22) for $y=5,-15 \leq x \leq 15$ values with $-2 \leq t \leq 2$ range and 2D plot of solution for $t=1$ with these values.


Figure 6. 3D of solution (23) for $y=0.2,-20 \leq x \leq 20$ values with $-5 \leq t \leq 5$ range and 2D plot of solution for $t=3$ with these values.

## Example 2:

For the find the soliton solutions of Eq. (2) we consider following equalities:
$u(x, y, t)=u(\eta), \eta=n(x+a y-h t)$.
Replace Eq. (24) into Eq. (2) and we get the following equation,

$$
\begin{equation*}
a n^{2} u^{\prime \prime \prime}+3 a n\left(u^{\prime}\right)^{2}+\left(a^{3}+2 h\right) u^{\prime}=0 . \tag{25}
\end{equation*}
$$

By making the $u^{\prime}=g$, transformation in Eq. (25), we find the following equation,

$$
\begin{equation*}
a n^{2} g^{\prime \prime}+3 a n g^{2}+\left(a^{3}+2 h\right) g=0 \tag{26}
\end{equation*}
$$

By using balance principle in Eq. (26), we obtain

$$
\begin{equation*}
k=l+2 \tag{27}
\end{equation*}
$$

If we give $l=1$ then $k=3$ we find the following equations,
$u(\eta)=\frac{a_{0}+a_{1} Q+a_{2} Q^{2}+a_{3} Q^{3}}{b_{0}+b_{1} Q}$,
$u^{\prime}(\eta)=\left(Q^{2}-Q\right) \times$
$\left[\begin{array}{l}\left(a_{1}+2 a_{2} Q+3 a_{3} Q^{2}\right)\left(b_{0}+b_{1} Q\right) \\ \frac{-b_{1}\left(a_{0}+a_{1} Q+a_{2} Q^{2}+a_{3} Q^{3}\right)}{\left(b_{0}+b_{1} Q\right)^{2}}\end{array}\right]$,
$u^{\prime \prime}(\eta)=\frac{Q^{2}-Q}{\left(b_{0}+b_{1} Q\right)^{2}}(2 Q-1) \times$
$\left[\begin{array}{l}\left(a_{1}+2 a_{2} Q+3 a_{3} Q^{2}\right)\left(b_{0}+b_{1} Q\right) \\ -b_{1}\left(a_{0}+a_{1} Q+a_{2} Q^{2}+a_{3} Q^{3}\right)\end{array}\right]+$
$\frac{\left(Q^{2}-Q\right)^{2}}{\left(b_{0}+b_{1} Q\right)^{3}}\left[\begin{array}{l}\left(b_{0}+b_{1} Q\right)^{2}\left(2 a_{2}+6 a_{3} Q\right)- \\ 2 b_{1}\left(b_{0}+b_{1} Q\right)\left(a_{1}+2 a_{2} Q+3 a_{3} Q^{2}\right) \\ +2 b_{1}^{2}\left(a_{0}+a_{1} Q+a_{2} Q^{2}+a_{3} Q^{3}\right)\end{array}\right]$.
(30)

We get soliton solutions of Eq. (2) in the following different cases;

## Case1:

$$
\begin{align*}
& a_{0}=-\frac{n b_{0}}{6}, a_{1}=n b_{0}-\frac{n b_{1}}{6} \\
& a_{2}=n\left(-b_{0}+b_{1}\right), a_{3}=-n b_{1}  \tag{31}\\
& a=\frac{3^{1 / 3} n^{2}+\left(-9 h+\sqrt{81 h^{2}-3 n^{6}}\right)^{2 / 3}}{3^{2 / 3}\left(-9 h+\sqrt{81 h^{2}-3 n^{6}}\right)^{1 / 3}}
\end{align*}
$$

Substituting the above values in Eq. (28), we acquire dark soliton solution of Eq. (2).

$$
\begin{align*}
& u_{1}(x, y, t)=\frac{-n^{2}}{6}(x+a y-h t) \\
& +\frac{n}{2} \tanh \left[\frac{n(x+a y-h t)}{2}\right], \tag{32}
\end{align*}
$$

where $a=\frac{3^{1 / 3} n^{2}+\left(-9 h+\sqrt{81 h^{2}-3 n^{6}}\right)^{2 / 3}}{3^{2 / 3}\left(-9 h+\sqrt{81 h^{2}-3 n^{6}}\right)^{1 / 3}}$.


Figure 7. 3D of solution (32) for $n=0.2755, a=4, y=0.5$, $k=-1,-25 \leq x \leq 25$ values with $-5 \leq t \leq 5$ range and 2D plot of solution for $t=0.5$ with these values.

Case2:
$a_{0}=\frac{\sqrt{a^{3}+2 h} b_{0}}{6 \sqrt{a}}, a_{1}=\frac{\sqrt{a^{3}+2 h}\left(-6 b_{0}+b_{1}\right)}{6 \sqrt{a}}$,
$a_{2}=\frac{\sqrt{a^{3}+2 h}\left(b_{0}-b_{1}\right)}{\sqrt{a}}$,
$a_{3}=\frac{\sqrt{a^{3}+2 h} b_{1}}{\sqrt{a}}, n=-\frac{\sqrt{a^{3}+2 h}}{\sqrt{a}}$.
Substituting the above values in Eq. (28), we acquire dark soliton solution of Eq. (2).
$u_{2}(x, y, t)=\frac{\sqrt{a^{3}+2 h}}{6 \sqrt{a}}(n x+n a y-n h t)$
$-\frac{\sqrt{a^{3}+2 h}}{2 \sqrt{a}} \tanh \left[\frac{(n x+n a y-n h t)}{2}\right]$,
where $n=-\frac{\sqrt{a^{3}+2 h}}{\sqrt{a}}$.


Figure 8. 3D of solution (34) for $n=-\sqrt{3}, a=1, y=5$,
$k=1,-20 \leq x \leq 20$ values with $-4 \leq t \leq 4$ range and 2D plot of solution for $t=2$ with these values.

Case3:

$$
\begin{align*}
& a_{0}=0, a_{1}=0, a_{2}=-\frac{i \sqrt{a^{3}+2 h} b_{1}}{\sqrt{a}}, \\
& a_{3}=\frac{i \sqrt{a^{3}+2 h} b_{1}}{\sqrt{a}}, b_{0}=0, n=-\frac{i \sqrt{a^{3}+2 h}}{\sqrt{a}} . \tag{35}
\end{align*}
$$

Substituting the above values in Eq. (28), we acquire trigonometric function solution of Eq. (2).
$u_{3}(x, y, t)=-\frac{\sqrt{a^{3}+2 h}}{2 \sqrt{a}} \times$
$\tan \left[\frac{\sqrt{a^{3}+2 h}(x+a y-h t)}{2 \sqrt{a}}\right]$,
(36)
where $n=-\frac{i \sqrt{a^{3}+2 h}}{\sqrt{a}}$.



Figure 9. 3D of solution (36) for $a=4, k=2, y=0.5$,
$-25 \leq x \leq 25$ values with $-3 \leq t \leq 3$ range and 2D plot of solution for $t=1$ with these values.

Case4:

$$
\begin{align*}
& a_{0}=-\frac{\sqrt{a^{3}+2 h} b_{0}}{6 \sqrt{a}}, a_{3}=-a_{2}-\frac{\sqrt{a^{3}+2 h} b_{0}}{\sqrt{a}} \\
& a_{1}=\frac{1}{6}\left(-a_{2}+\frac{5 \sqrt{a^{3}+2 h} b_{0}}{\sqrt{a}}\right)  \tag{37}\\
& b_{1}=\frac{\sqrt{a} a_{2}}{\sqrt{a^{3}+2 h}}+b_{0}, n=\frac{\sqrt{a^{3}+2 h}}{\sqrt{a}}
\end{align*}
$$

Substituting the above values in Eq. (28), we acquire dark soliton solution of Eq. (2).

$$
u_{4}(x, y, t)=\frac{i \sqrt{17} \sqrt{a^{3}+2 h}(x+a y-h t)}{6 \sqrt{a}}
$$

$$
\begin{equation*}
-\frac{i \sqrt{17}}{2} \tanh \left[\frac{\sqrt{a^{3}+2 h}(x+a y-h t)}{2 \sqrt{a}}\right] \tag{38}
\end{equation*}
$$




Figure 10. 3D of solution (38) for $a=2, k=1, y=1$,
$-20 \leq x \leq 20$ values with $-5 \leq t \leq 5$ range and 2D plot of solution for $t=2$ with these values.

## 4. Conclusion

In this made study, we discussed GKM, which is one of the NLEEs solution methods. We applied this discussed method to the $(2+1)$-dimensional DJKM equation and the $(2+1)$ dimensional DLWS and so we got some soliton solutions of equation and system being studied. At the same time, we drew the drawings of the 2D and 3D graphics of the found soliton solutions by giving certain values. Thus, it has been seen that GKM is a reliable and exact solution method in obtaining NLEEs solutions. In future studies, GKM can be used in research of other NLEEs.

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